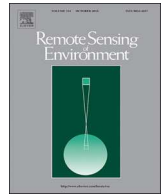




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# Deep learning-based air temperature mapping by fusing remote sensing, station, simulation and socioeconomic data



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## ABSTRACT

Air temperature (Ta) is an essential climatological component that controls and influences various earth surface processes. In this study, we make the first attempt to employ deep learning for Ta mapping mainly based on space remote sensing and ground station observations. Considering that Ta varies greatly in space and time and is sensitive to many factors, assimilation data and socioeconomic data are also included for a multi-source data fusion based estimation. Specifically, a 5-layers structured deep belief network (DBN) is employed to better capture the complicated and non-linear relationships between Ta and different predictor variables. Layer-wise pre-training process for essential features extraction and fine-tuning process for weight parameters optimization ensure the robust prediction of Ta spatio-temporal distribution. The DBN model was implemented for 0.01° daily maximum Ta mapping across China. The ten-fold cross-validation results indicate that the DBN model achieves promising results with the RMSE of 1.996 °C, MAE of 1.539 °C, and R of 0.986 at the national scale. Compared with multiple linear regression (MLR), back-propagation neural network (BPNN) and random forest (RF) method, the DBN model reduces the MAE values by 1.340 °C, 0.387 °C and 0.222 °C, respectively. Further analysis on spatial distribution and temporal tendency of prediction errors both validate the great potentials of DBN in Ta estimation.

## 1. Introduction

Air temperature (Ta) is one of the fundamental meteorological parameters and has been associated with a wide range of studies including disease vectors propagating and human health (Li et al., 2010; Lowen et al., 2007), terrestrial hydrology and phenology (Lin et al., 2012; Wang et al., 2009), climate and environment change (Robeson, 2002). Typically, Ta is measured through monitoring stations at 2 m above the ground with high precision. However, the spatial distribution of the meteorological stations may be extremely sparse on a large scale, especially in some underdeveloped and complicated terrain areas. Hence, traditional spatial interpolation methods, such as Kriging, Inverse Density Weighting (IDW) and Spline interpolation have been used to generate spatially continuous Ta. However, these interpolation methods are still limited to the station density and the complexity of different environmental conditions (Shi et al., 2017; Ung et al., 2001).

Related researches have confirmed that there exists an energy exchange between land surface and near-surface atmosphere, land surface

temperature (LST) retrieved from the thermal infrared remote sensing truly has a strong physical relationship with the Ta. Recently, the satellite-derived LST products with high temporal and spatial resolution is widely applied to estimate Ta (Colombi et al., 2007; Stoll and Brazel, 2013; Lin et al., 2012; Tomlinson et al., 2012; Zakšek and Schroedter-Homscheidt, 2009). Nevertheless, LST cannot be directly regarded as a proxy for Ta in terms of their different physical meaning and magnitude (Jin and Dickinson, 2010), and the LST-Ta relationship is sensitive to many spatio-temporal factors in reality, especially for the maximum Ta (Jin et al., 1997; Lu et al., 2018). How to accurately estimate Ta with a large spatial distribution has become one of the research hotspots in the field of remote sensing. Various satellite-based parameterization algorithms have been implemented to estimate Ta and can be divided into three main types (Ho et al., 2014; Zhu et al., 2017).

The first type is the temperature-vegetation index (TVX) method, which is a spatial method based on the presumption that vegetation canopy temperature approximates near-surface Ta in an absolutely thick canopy (Nieto et al., 2011; Prihodko and Goward, 1997; Zhang

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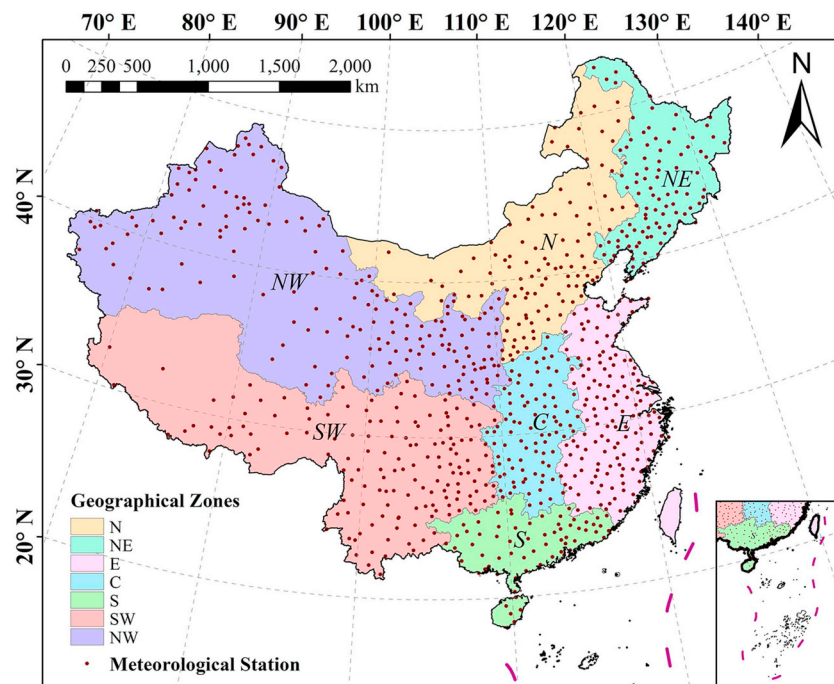


Fig. 1. Map of the study area and the geographical distribution of meteorological stations. N, E, S, NE, NW, SW and C denotes northern China, eastern China, southern China, northeastern China, northwestern China, southwestern China and central China, respectively.

et al., 2014). The strong negative correlation between LST and normalized difference vegetation index (NDVI) is adopted to extrapolate the Ta. According to Xu et al. (2011), some additional rules had been made for the TVX method to broaden the applied range, and the results demonstrated good accuracy and applicability in cropland areas in crop growing seasons. In another study, Zhu et al. (2013) improved the accuracy of daily maximum Ta estimation by using the TVX method. Although TVX method performed adequately in some studies, the basic presumption makes it unfeasible to estimate Ta for regions or seasons without high vegetation cover (Vancutsem et al., 2010; Zhu and Zhang, 2011).

The second type is the energy balance method that has a clear physical mechanism. The net radiation is deemed to be equal to the sum of the surface's sensible, soil and latent heat fluxes (Meteotest, 2010; Zhang et al., 2015). According to the energy balance equation, Ta can be linked to the LST and other surface environmental parameters. Sun et al. (2005) once presented a thermodynamics-based method to derive the relationship between Ta and LST by using aerodynamic resistance and a crop water stress index obtained from Moderate Resolution Imaging Spectroradiometer (MODIS) data. In the work conducted by Hou et al. (2013), an Energy Balance Bowen Ratio model was developed with the mean retrieval error of approximately 2.21 °C. This method shows good portability and universality, however, it may need comprehensive parameters as inputs, which are hard to obtain directly (Mostovoy et al., 2006).

The third and most commonly-used type is the statistical method, which is typically based on the regressive relationship between Ta and other variables. Simple statistical model only structures a linear regression between LST and Ta (Shi et al., 2017; Vogt et al., 1997), while advanced statistical models, such as multiple regression model, artificial neural network and machine learning models use a mass of auxiliary variables to establish linear or non-linear relationship (Fu et al., 2011; Mohsenzadeh Karimi et al., 2018; Singh et al., 2006). For instance, Janatian et al. (2017) proposed an advanced statistical framework by constructing fourteen statistical models through a stepwise regression analysis based on MODIS LST data and other variables. The geographically weighted regression (GWR) model, as a widely used

statistical approach, was once used and confirmed to have better performance than ordinary linear regression (OLS) model (Yao and Zhang, 2013). Besides, daily GWR models were developed to produce daily Ta for urban and surrounding areas in the conterminous United States recently (Li et al., 2018). The increasing popularity of machine learning stemmed in Ta estimation field in recent years. To date, various machine learning models have been developed and reported successfully in Ta estimation. For example, Li and Zha (2018) applied the random forest model (RF) to estimate relative humidity and temperatures in hot summer over China and achieved acceptable prediction errors. Noi et al. (2017) estimated daily Ta from dynamic combinations of MODIS LST data by comparing multiple linear regression (MLR), cubist regression (CB), and RF. Besides, Xu et al. (2018) even implemented and compared ten machine learning algorithms to estimate monthly Ta in the Tibetan Plateau and the results showed that machine learning algorithms had great potentials in Ta estimation.

As mentioned above, previous studies have confirmed that machine learning algorithms have great advantages in Ta estimation due to the capacity of handling non-linear relationships. Deep learning, as a well-known new generation of technology in machine learning methods, has been proven to be very promising in many domains of researches (Kuwata and Shibasaki, 2015; Shen et al., 2018; Song et al., 2016). However, to the best of our knowledge, deep learning has never been used for Ta estimation. Hence, it is of great interest to examine whether deep learning technique show more advantages for this complicated non-linear problem in Ta estimation. For this, a 5-layers deep belief network (DBN) is structured to establish the relationship between station Ta observation and multi-source data including remotely sensed data, socioeconomic data and assimilation data. The network model is then used for high spatio-temporal resolution Ta mapping across China. Its effectiveness and advantages are validated by extensive experiments.

## 2. Study area and data

### 2.1. Study area

China is selected as the study area in this research (Fig. 1). The total

area covers approximately 9.6 million km<sup>2</sup>, lies between latitudes 3°N and 54°N, and between longitudes 73°E and 136°E. Additionally, China shows highly spatial heterogeneity of land-cover types, the plains and basins account for about 33% of the land area, while mountainous, hills and plateaus account for about 67%. According to the geographical division of China, there are seven zones including eastern, northern, southern, central, southwestern, northwestern and northeastern China. In general, the terrain is high in the southwest but low in the east with the whole elevation ranging from -154 m to 8848 m. The southwest of China has the tallest Tibetan Plateau in the world, with an average elevation of > 4000 m. Due to the highly complex terrain, the climate in China varies greatly in space and is mainly dominated by dry seasons and wet monsoon.

## 2.2. Datasets

### 2.2.1. Meteorological Ta observation

The meteorological Ta observations used in this study were obtained primarily from the China Meteorological Data Service Center (CMDSC, <http://data.cma.cn/>). A total of 829 meteorological stations spread in mainland China were used. As shown in Fig. 1, there was a higher density of the stations located in southern, eastern and central China compared with the relatively sparse station distributions in the northwestern and southwestern areas, especially in Tibetan Plateau. Daily maximum Ta of these stations in 2015 was provided. Also, the accuracy and integrity of the observations have been improved after original calibration and quality control. In addition, the geographical and temporal parameters of each station provided simultaneously with the Ta observations were also used in this study, including latitude (Lat), longitude (Lon), month of year (Mon) and day of year (Doy).

### 2.2.2. Remotely sensed data

In this study, the remotely sensed datasets included LST, NDVI, land cover (Lc) and elevation (Ele).

**LST:** MODIS LST products have been proved to be an effective variable for estimating Ta in many previous studies (Chen et al., 2016; Noi et al., 2016; Zhang et al., 2011). Daily LST product, MOD11A1 (Terra Daily Land Surface Temperature and Emissivity) across China for the year 2015 were utilized in this study. MOD11A1 provided per-pixel temperature with a spatial resolution of 1 km sin grid, which was retrieved by the generalized split-window algorithm (Vancutsem et al., 2010). The accuracy of LST has been validated and reported to be better than 1 K under clear sky conditions in most cases (Wan et al., 2002; Wan, 2014). In this study, only daytime land surface temperature (LSTD) with the overpass time around 10:30 am local time was used. Considering that LSTD may be influenced by the observed angle, view zenith angle (Vangle) of day observation was also extracted from MOD11A1 product along with LSTD at 1 km spatial resolution.

**NDVI:** NDVI data was extracted from the MOD13A2 (Terra 16-Day Vegetation Index) product with a 1 km resolution. The 16-day NDVI product was used due to NDVI values do not change significantly within 16 days.

**Land cover:** Annual Terra and Aqua combined MODIS land cover product (MCD12Q1) for 2015 was used in this study. We reclassified land cover categories into six types across China including cropland, woodland, grassland, urban and built, water and barren in order to make it easier to assess the effect of land cover on the model performance. All the MODIS data used in this study were downloaded from the Level-1 and Atmosphere Archive and Distribution System Distributed Active Archive Center (LAADS DAAC, <https://ladsweb.modaps.eosdis.nasa.gov/search/>).

**Elevation:** Elevation data was obtained from the CGIAR Consortium for Spatial Information (CGIAR-CSI, <http://srtm.csi.cgiar.org/index.asp>), which provided global resampled Shuttle Radar Topography

Mission (SRTM) digital elevation product with the spatial resolution of approximately 250 m.

### 2.2.3. Assimilation data

The Global Land Data Assimilation System (GLDAS) makes full use of the advanced generation of ground and space-based observation systems and provides a series of long-term gridded land surface states and flux parameters (Fang et al., 2009; Rodell et al., 2004). GLDAS version 2.1 datasets were downloaded from the NASA Goddard Earth Sciences Data and Information Services Center (GES DISC, <https://disc.gsfc.nasa.gov/>). Several assimilation data products such as wind speed (WS), soil moisture content at 0–10 cm underground (SoilMoi), albedo (Albe) and direct evaporation from bare soil (Esoil) with 0.25 degree and 3-hourly resolution were utilized, which were simulated with the Noah Land Surface Model 3.3 in Land Information System Version 7. The 3-hourly assimilation data were aggregated to a daily scale in this study.

### 2.2.4. Socioeconomic data

Socioeconomic factors were also taken into consideration to represent the influence of anthropogenic heat on Ta in a sense. Road density (RoadD) data was calculated within a 1° search radius by using the road network vector data downloaded from the OpenStreetMap (OSM, <https://www.openstreetmap.org/>). Only primary road, secondary road, tertiary road, trunk road, motorway and unclassified road were selected on account of the complexity of calculation. Besides, population density (PopD) data for 2015 was available on the Socioeconomic Data and Applications Center (SEDAC, <http://sedac.ciesin.columbia.edu/>). The original global raster data were produced with a 30 arc-second spatial resolution (CIESIN, 2017).

### 2.2.5. Data pre-processing

In total, we introduced station daily maximum Ta observation with some geographical and temporal parameters, remotely sensed data, assimilation data and socioeconomic data to conduct our work. All the data and their abbreviations were listed in Table 1. More specifically, the MODIS Reprojection Tool software was used to deal with the MODIS data from the original HDF-EOS format to GeoTIFF format. For assimilation data, the ArcPy site package of Python provided a productive way to process the original multidimensional netCDF file into a separate raster layer. For single raster data like elevation, population density and road density, pre-processing and processing are

**Table 1**  
Abbreviations of the data used in this study.

Abbreviation	Data	Spatial resolution	Temporal resolution
Ta	Air temperature	–	1 day
Lat	Latitude	–	–
Lon	Longitude	–	–
Doy	Day of year	–	–
Mon	Month of year	–	–
LSTD	Daytime land surface temperature	1000 m	1 day
NDVI	Normalized difference vegetation index	1000 m	16 days
Vangle	View zenith angle of day observation	1000 m	1 day
Ele	Elevation	250 m	–
Lc	Land cover	500 m	1 year
PopD	Population density	30"	5 years
RoadD	Road density	Polyline	–
WS	Wind speed	0.25°	3 h
SoilMoi	Soil moisture content	0.25°	3 h
Albe	Albedo	0.25°	3 h
Esoil	Direct evaporation from bare soil	0.25°	3 h

implemented by using ArcGIS software. After batch pre-processing of image mosaic, format conversion and image clip, remotely sensed data, assimilation data and socioeconomic data were reprojected to the same geographic coordinates system. For this work, nearest neighbor was chosen for resampling the raster data to the  $0.01^\circ \times 0.01^\circ$  grid cell for consistency. Then, the nearest neighbor method was also used to match the point observations and raster data by extracting multiple corresponding variable values on the grid where each meteorological station was located. Considering that satellite-based data may be vacant or unusual due to the cloud cover or contamination and sensor fault (Shen et al., 2015; Wan, 2014; Zeng et al., 2018), eliminating unfilled and outlier data was necessary for the purpose of establishing effective data pairs. In total, 107,578 matched samples with both daily maximum Ta and all predictor variable values were identified to form the experimental datasets. It should be noted that Ele and PopD value are highly differentiated in space, which may lead to unsatisfactory results. In order to narrow the range of these values, the original value is mapped by an exponential function in this study.

### 3. Methodology

#### 3.1. Deep belief network

As the second generation of neural network, deep learning method was employed in this study to simulate the non-linear relationship between Ta observation and multi-source data. Compared with some general machine learning methods, deep learning makes it closer to artificial intelligence (Deng and Yu, 2014; Lecun et al., 2015). Deep belief network, as a Bayesian probability generation model, is developed for the first attempt to estimate Ta. The classic DBN can be regarded as a combination of multiple layers of simple, unsupervised networks, and usually is superposed by many restricted Boltzmann machines (RBM) layers and a back-propagation (BP) layer. Fig. 2 shows the structure of the DBN with two RBM layers as an example. Each RBM is a two-layers neural network, which consists of a visible input layer  $V$  and a hidden layer  $H$  (Hinton et al., 2006). As shown in Fig. 2, the

training procedure of DBN can be treated as an efficient unsupervised layer-wise fashion (Hinton, 2009). Taking one RBM for example, supposing there are  $n$  neurons in the visible layer and  $m$  neurons in the hidden layer, the neurons have fully undirected connections between the two layers but no connections existing between neurons in the same layer. Generally, the parameters of the RBM such as weight matrix  $W$ , bias  $a$  and  $b$  are updated by the contrastive divergence (CD) algorithm (Hinton et al., 2006). The updating weight matrix  $\Delta W_{ij}$  can be expressed as follows:

$$\Delta W_{ij} = \varepsilon (\langle V_i H_j \rangle_{data} - \langle V_i H_j \rangle_{model}) \tag{1}$$

where  $V_i$  and  $H_j$  are the states of the  $i$ th visible neuron and the  $j$ th hidden neuron, respectively;  $\varepsilon$  is the learning rate;  $\langle \rangle_{data}$  represents the expectation with respect to the distribution of the training samples;  $\langle \rangle_{model}$  is the expectation under the partial derivative of the re-constructed model. Bias  $a$  and  $b$  are updated in a similar way.

In this study, we utilized the DBN model by fusing Ta observations with geographical and temporal parameters, remotely sensed data, assimilation data and socioeconomic data. The structure of the model can be given by Eq. (2):

$$Ta = f(LSTD, NDVI, Vangle, Ele, Lc, Lat, Lon, Doy, Mon, WS, SoilMoi, Albe, Esoil, PopD, RoadD) \tag{2}$$

where  $f()$  means the non-linear estimation function that the DBM model needs to model.

The flow chart of the DBN model used in this study is shown in Fig. 3, and the process can be summarized as pre-training, fine-tuning and prediction which is described in detail in the previous literature (Li et al., 2017). Once we put all the predictor variables into the model, they are recognized as the visible layer in the first RBM. The whole pre-training can be regarded as the process of extracting essential features from the input data that are associated with daily maximum Ta by using the feature optimization algorithm. This process is repeated from the lowest layer to the highest layer without supervision. Through the layer-by-layer pre-training until the hidden layer of the last RBM, the

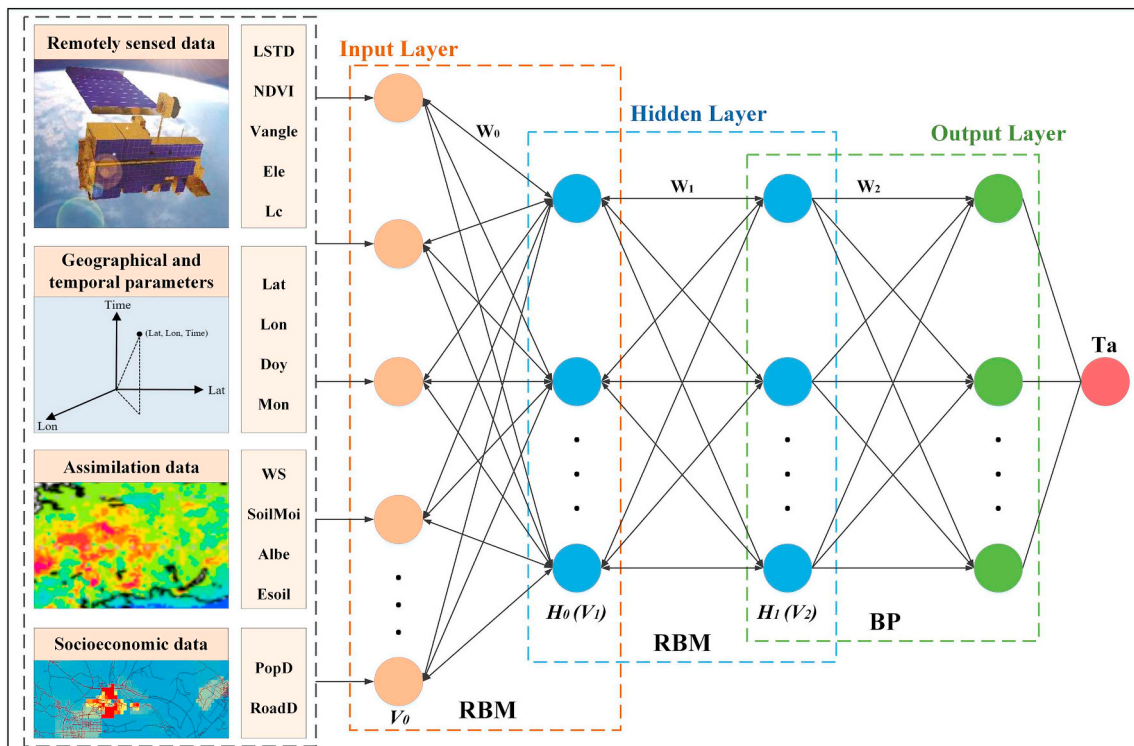


Fig. 2. The structure of the DBN model.

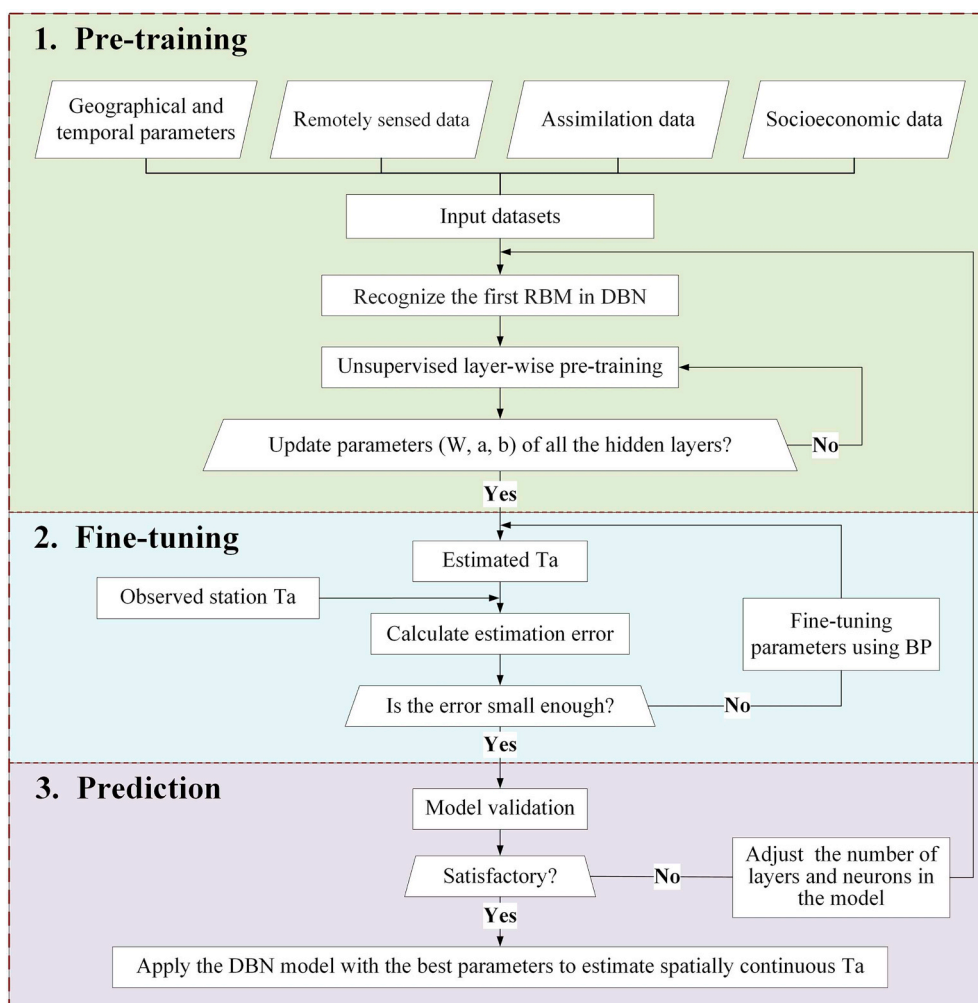


Fig. 3. The flow chart of the DBN model to estimate daily maximum  $T_a$ .

parameters can be obtained approximately close to their ideal values. In addition, we can obtain the estimated  $T_a$ , which are compared with the observed values. Then, the BP algorithm is adopted for fine-tuning all the weight parameters of the DBN model to get a refined prediction until the estimated error is small enough. Additionally, model cross-validation is implemented to evaluate whether the estimation results are accurate enough, otherwise we must constantly adjust the number of hidden layers in the model and the neurons in each hidden layer. Finally, a model with the best parameters can be applied to estimate spatially continuous  $T_a$  at the national scale. After many experiments, a 5-layers DBN model was developed in this study including one input layer, one output layer and three hidden layers. The number of neurons in each hidden layer is designed as 25, 20 and 15, respectively.

### 3.2. Model validation

To better evaluate the performance of each model, the ten-fold cross-validation approach was conducted to test the model predictive ability and overfitting problems (Rodríguez et al., 2010). In ten-fold cross-validation, all the samples were randomly split into ten groups of approximately equal size. Each group was withheld in turn as the validation dataset to assess the model performance, while the rest of the nine groups were used for model fitting. This procedure was repeated for ten times until each group had been tested exactly once as the validation part and got corresponding predictions. A set of statistical indicators-Pearson correlation coefficients (R), mean absolute error (MAE) and root mean square error (RMSE) were calculated to evaluate

the model accuracy by comparing the estimated results with the real corresponding station-based observations.

## 4. Results

### 4.1. Descriptive statistics

Pearson correlation coefficients were calculated in this study to evaluate the strong linear or non-linear relationship between predictor variables and daily maximum  $T_a$  observations. The R values of all variables except Lc are presented in Fig. 4, since the Lc represents the categorical attributes rather than specific numerical meanings. It can be observed that LSTD has a strong correlation with  $T_a$  ( $R > 0.9$ ). NDVI, Albe, Esoil, SoilMoi, Lat, Ele, PopD and RoadD have a relatively moderate correlation with  $T_a$  with the absolute R values between 0.2 and 0.6. Those absolute R values below 0.2 indicate that WS, Vangle, Lon, Doy and Mon have an extremely weak correlation with  $T_a$ .

Despite a strong positive correction between LSTD and daily maximum  $T_a$  is observed for the whole samples, the LSTD- $T_a$  relationship is not constant under different circumstances. To understand this phenomenon in detail, the correlation between LSTD and  $T_a$  was tested for different months, elevation ranges and latitude ranges to assess the spatial and temporal impact. From the results listed in Table 2, it is evident to note that the LSTD- $T_a$  relationship is significantly influenced in diverse environments especially for different months with the distinct R value disparity reaches nearly 0.4 between May and January. As a whole, LSTD is more related to  $T_a$  in the areas with low elevation and

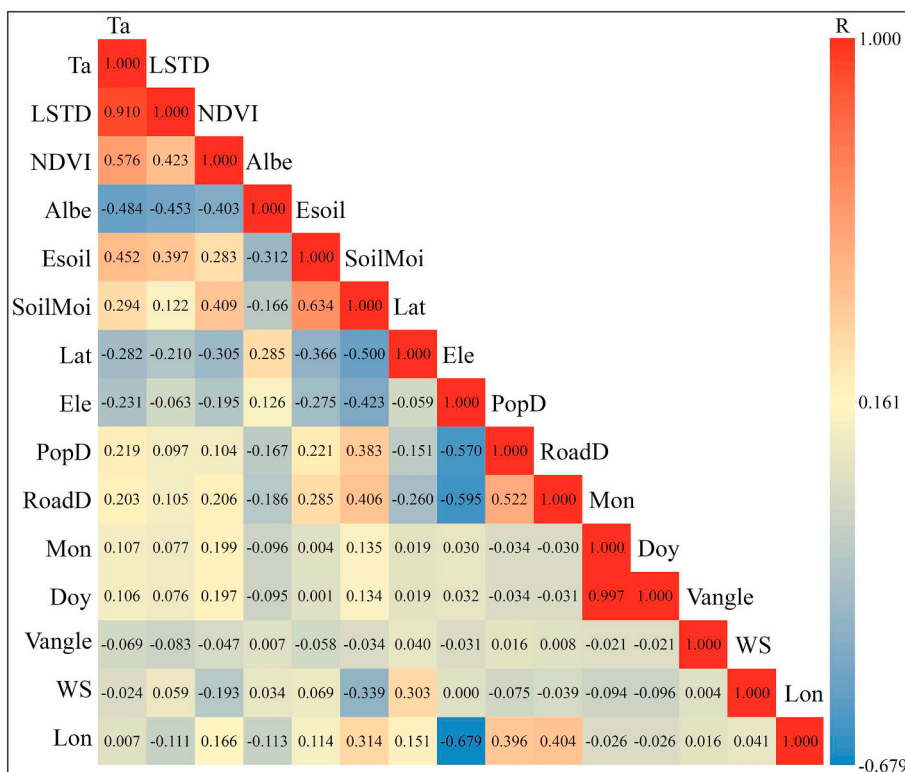


Fig. 4. Pearson correlation coefficient among the predictor variables and Ta.

Table 2

The R between LSTD and Ta for different months, elevation ranges and latitude ranges.

Month/R	Elevation (m)/R	Latitude (°)/R
Jan. 0.926	Jul. 0.593	< 1000 0.954
Feb. 0.857	Aug. 0.549	1000–2000 0.918
Mar. 0.814	Sep. 0.638	2000–3000 0.855
Apr. 0.701	Oct. 0.799	3000–4000 0.761
May. 0.527	Nov. 0.899	> 4000 0.817
Jun. 0.541	Dec. 0.912	> 50 0.978

high latitude as well as in the seasons with relatively low temperature. This phenomenon might lead to an obvious influence on the accuracy of Ta estimation.

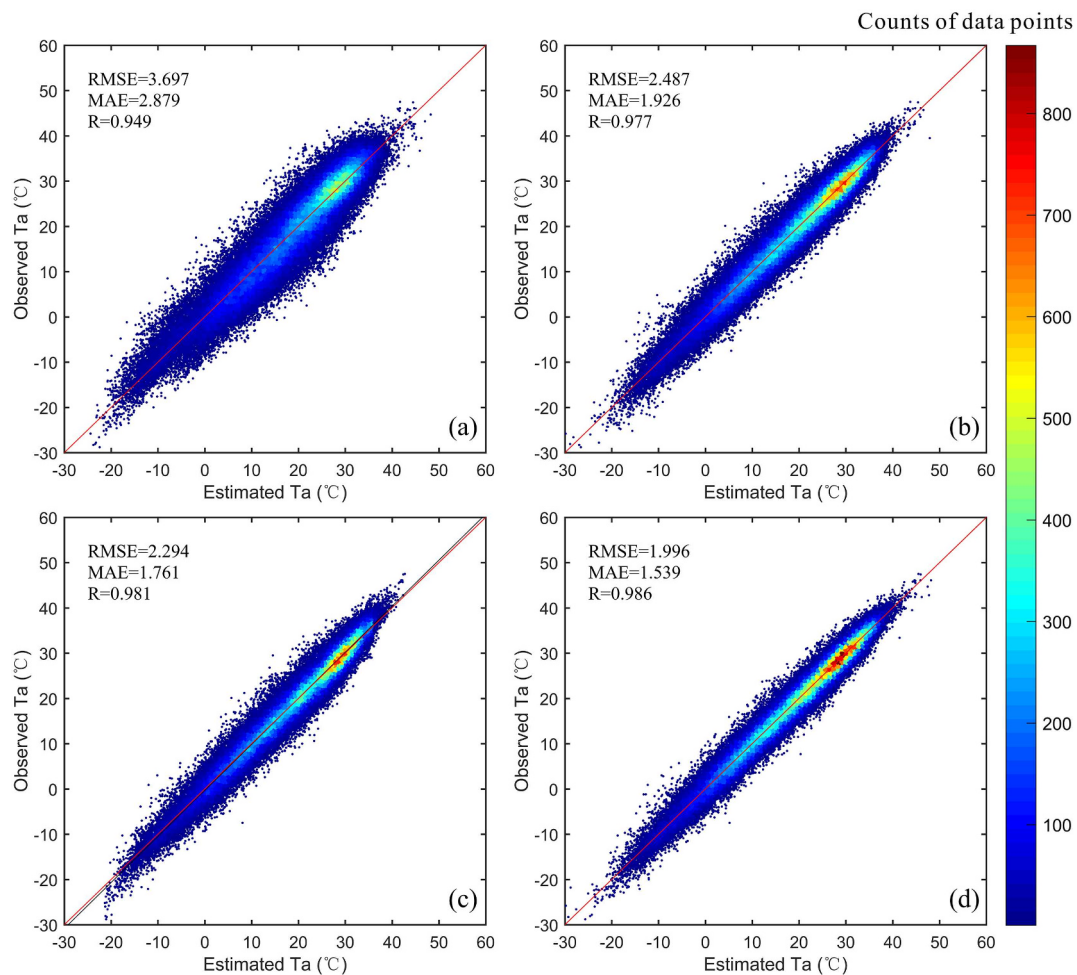
4.2. Overall performance of the DBN model

By applying all the above variables, daily maximum Ta across China was estimated and validated. Fig. 5 shows the overall performance for the DBN and other three contrast models. From the point density plots, the fitting line (the line in black) of the four models are nearly close to the 1:1 line (the line in red). However, it should be noted that MLR shows the most dispersed scatter dots, which indicates that using the linear model to derive Ta may cause relatively large errors in some conditions due to the complex relationships between LSTD and Ta. Unlike MLR, traditional BPNN is based on non-linear fitting, and the result is better than MLR but not ideal due to the relatively simple structure of the model. RF, as a new machine learning model, is also a non-linear technique which makes estimations by averaging an ensemble of individual regression trees, shows better results than MLR and BPNN. Especially, owing to the best capabilities of fitting non-linear relationships, deep learning method achieves the most accurate estimations with most of the scatter dots gathered close to the 1:1 line. From another comprehensive and quantitative perspective, the

cross-validation results provide a better understanding of the different performances for each model. Overall, all the models present acceptable fits with RMSE ranging from 1.996 °C to 3.697 °C, MAE ranging from 1.539 °C to 2.879 °C, and R ranging from 0.949 to 0.986, respectively, at the national scale. The best performance is achieved in deep learning method with the highest R value and lowest RMSE and MAE, followed by the RF and BPNN. Compared with the worst estimated result derived from the MLR, the RMSE decreases by 1.701 °C (from 3.697 to 1.996), MAE decreases by 1.340 °C (from 2.879 to 1.539) and R increases by 0.037 (from 0.949 to 0.986), which confirms that deep learning method has great potential capabilities in estimating Ta at the national scale. The reason may be that deep learning method can better simulate the potential characteristics of the variables, which are not intensively correlated with Ta than conventional methods like MLR, BPNN and RF.

4.3. Spatial evaluation of model performance

The model performance for the spatial pattern was evaluated, and the distribution of MAE for each meteorological station were shown in Fig. 6. There are significant variations existing in MAE spatial distribution. For MLR, the MAE range from 1.276 to 10.318 °C with a huge fluctuation from one station to another, and the MAE of 86% of all stations are higher than 2 °C (Fig. 6a). Most of the stations with high MAE are located in the southwestern and northwestern China. For BPNN, there are 30% of all stations report the MAE higher than 2 °C and most of them are located in southwestern, northwestern and northern China (Fig. 6b). For RF, the maximum MAE is reduced to 4.385 °C with 17% of all stations are higher than 2 °C. Spatially, the MAE exhibits relatively low values in southern and central China (Fig. 6c). Compared with the above three methods, the accuracy of the DBN model has been significantly improved with only 0.04% of all stations have relatively high estimation error (> 2 °C) in total (Fig. 6d). It is clear that the number of those stations with the MAE value > 2.5 °C is reduced to 5 for DBN, while there are 440, 37 and 23 stations for MLR, BPNN and RF, respectively. Additionally, the minimum and maximum MAE value



**Fig. 5.** The point density plots of the observed and estimated daily maximum  $T_a$  for the cross-validation results. (a)–(d) represent the results for MLR, BPNN, RF and DBN models, respectively. The line in black is the linear regression of the scattered dots; the line in red is the 1:1 line as reference. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

for DBN are also reduced to about 0.742 and 4.289 °C, respectively. Most of the MAEs change relatively gently with the values fluctuate steadily between 1 and 2 °C for DBN. These results illustrate that deep learning method is more stable than conventional methods for most stations. In addition, from the overall distribution of MAEs in each model, stations located closer to the shoreline, where the climate is often dominated by the ocean, perform relatively poor. This is also consistent with some previous studies (Benali et al., 2012; Pelta and Chudnovsky, 2017). Besides, the stations located in southern China achieve better performance than northwestern stations in this study. This may benefit from the dense station distribution and the uncomplicated topographic and environmental conditions in southern China. In this study, the kernel density tool in ArcGIS was used to calculate the density for each station feature. Then, the relationship between the spatial density of stations and model performance was analyzed in detail. As shown in Fig. 7, the model performance in spatial is obviously influenced by the distribution of stations especially for MLR. Overall, there was a positive correlation between station density and model accuracy. That's to say, the more clustered the stations, the higher accuracy of the model. Compared with MLR, BPNN and RF, the lowest slope shown in Fig. 7d can reflect that DBN can reduce the effect of station density on accuracy to a certain extent.

Previous researches have revealed that land cover types have a significant influence on the relationship between LSTD and  $T_a$  (Cheng et al., 2008; Lin et al., 2012; Marzban et al., 2018). The model performance for different land cover types is compared by calculating the

MAE. As shown in Fig. 8a, there is no doubt that the DBN model performed the best. However, the MAE varies at different land cover types for DBN, as well as in other models. The difference between the maximum and minimum MAE for DBN approximately reach to 0.325 °C. In general, higher MAE values can be seen in woodland, barren and grassland. As for those stations located near the urban and built land, water and cropland, relatively better model performance is exhibited.

Apart from the above land cover types, model performance for different latitude ranges is also discussed in our study. The results shown in Fig. 8b suggest that DBN is superior to the other three models for all latitude ranges. For the DBN model, the MAE value varies from 1.331 °C to 1.887 °C. Overall, higher latitude may lead to poorer model performance except the latitude range from 20 to 30°. In this range, BPNN, RF and DBN all achieve the best model performance. For MLR, the model performance shows a wave-shaped curve for different latitude ranges.

In addition, it is widely acknowledged that  $T_a$  is highly related to elevation. In most cases,  $T_a$  may decrease as the elevation increases. Meanwhile, the correlation coefficient between LSTD and  $T_a$  shows obvious variations for different elevation ranges as mentioned in Section 4.1. Hence, the model performance for different elevation ranges is also analyzed in terms of MAE. From Fig. 8c, we can find out that models perform differently for specific elevation ranges, among which DBN model performs the best and shows the smallest MAE variation, followed by RF, BPNN and MLR in turn. Generally, the model performance for DBN is weakening by the elevation increasing.

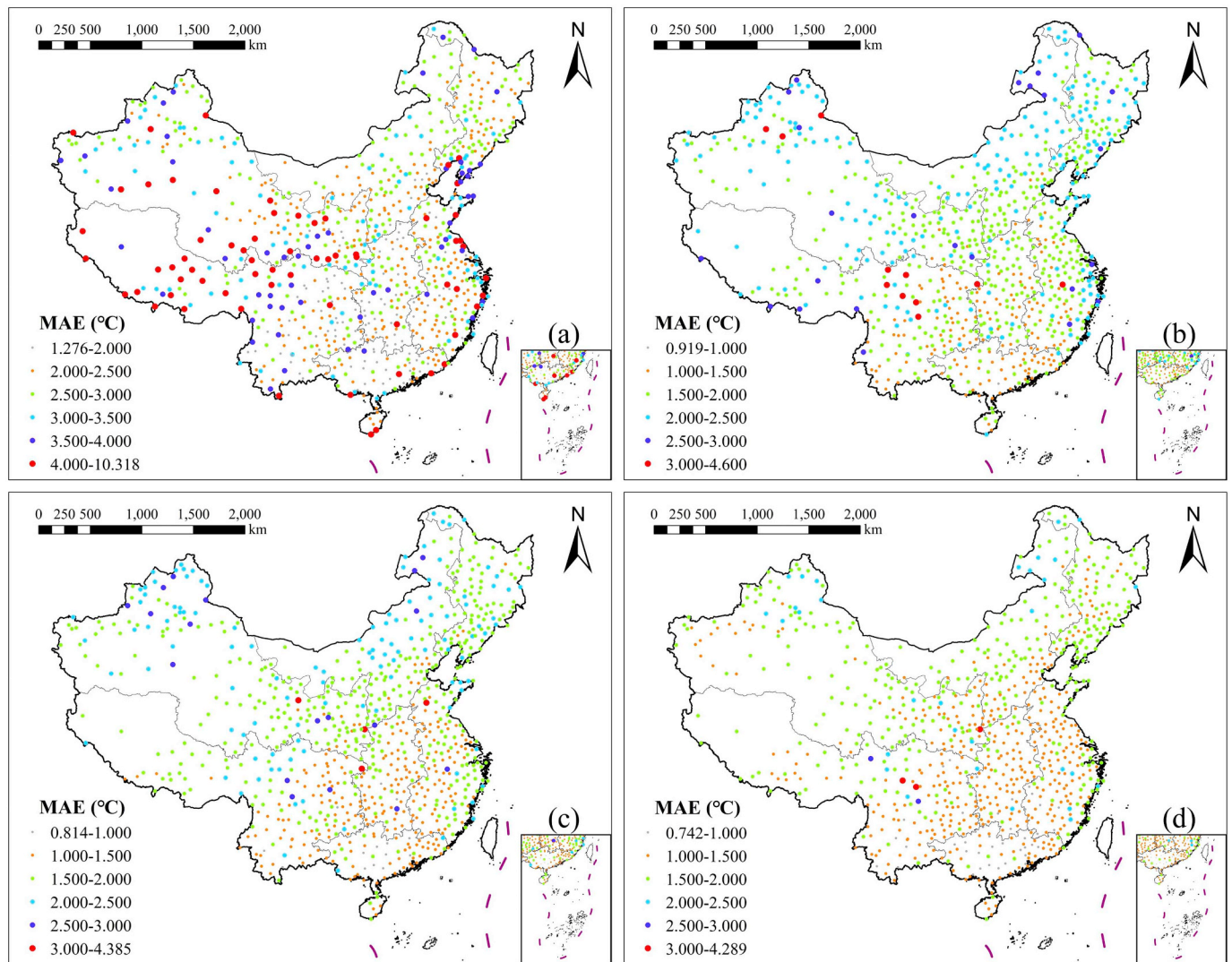


Fig. 6. The spatial distribution of MAE for each meteorological station. (a) MLR, (b) BPNN, (c) RF, (d) DBN.

However, it is noteworthy to mention that there is a reverse when the elevation is above 4000 m.

#### 4.4. Temporal evaluation of model performance

For temporal analysis, model performance at the monthly scale is evaluated. Fig. 9 shows the box plots of residual Ta values (estimated-observed) distribution for each month. It is clear that the medium of residuals for MLR is fluctuating. Besides, the medium of residual values from June to August are obviously below 0 °C, which indicates that MLR tends to underestimate daily maximum Ta in these months. Compared with MLR, BPNN and RF methods, the medium of residuals for DBN all fall close to 0 °C for each month, which indicates that deep learning method is not prone to cause overestimation or underestimation. Besides, DBN exhibits the lowest uncertainties in residual change than other models (Fig. 9d). In April, the residuals in BPNN and RF show obviously large fluctuations than the other months. Once we used deep learning method, this monthly variation can be reduced to a certain extent as shown in Fig. 9d.

From the MAEs for each model, we can see clearly that model uncertainties are rather high in term of month. Even for the DBN model, the difference between the maximum and minimum MAEs also reaches to about 0.494 °C (Fig. 9d). The best model performance for the DBN model is achieved in August with the MAE of 1.248 °C. More

specifically, it's interesting to find that the DBN model seems to show the tendency to perform better in hot months, which is not consistent with our expectations. Because relatively low correlation coefficient between LSTD and Ta can be found in these months as demonstrated in Section 4.1. This finding reveals that model performance at specific circumstances may not strictly depend on the correlation coefficient between LSTD and Ta due to the efficient influence from other predictor variables. Overall, all the above-mentioned findings reinforce the necessity of considering temporal factors in Ta estimation models. To get a thorough understanding of this point, seasonal DBN models are worth attempting in the future work.

## 5. Discussion

### 5.1. DBN structure comparison

To investigate the model performance, different adjustments of DBN structures were compared and the result was shown in the table below (Table 3). With the increase of the number of DBN layers and neurons, the accuracy of the model increases obviously. However, when the hidden layer of DBN reaches to 4, the model performance tends to be stable. It's noteworthy that over-parameterized model may lead to overfitting. Besides, saving computational cost is another factor that we should take into consideration. Therefore, the DBN structure with three



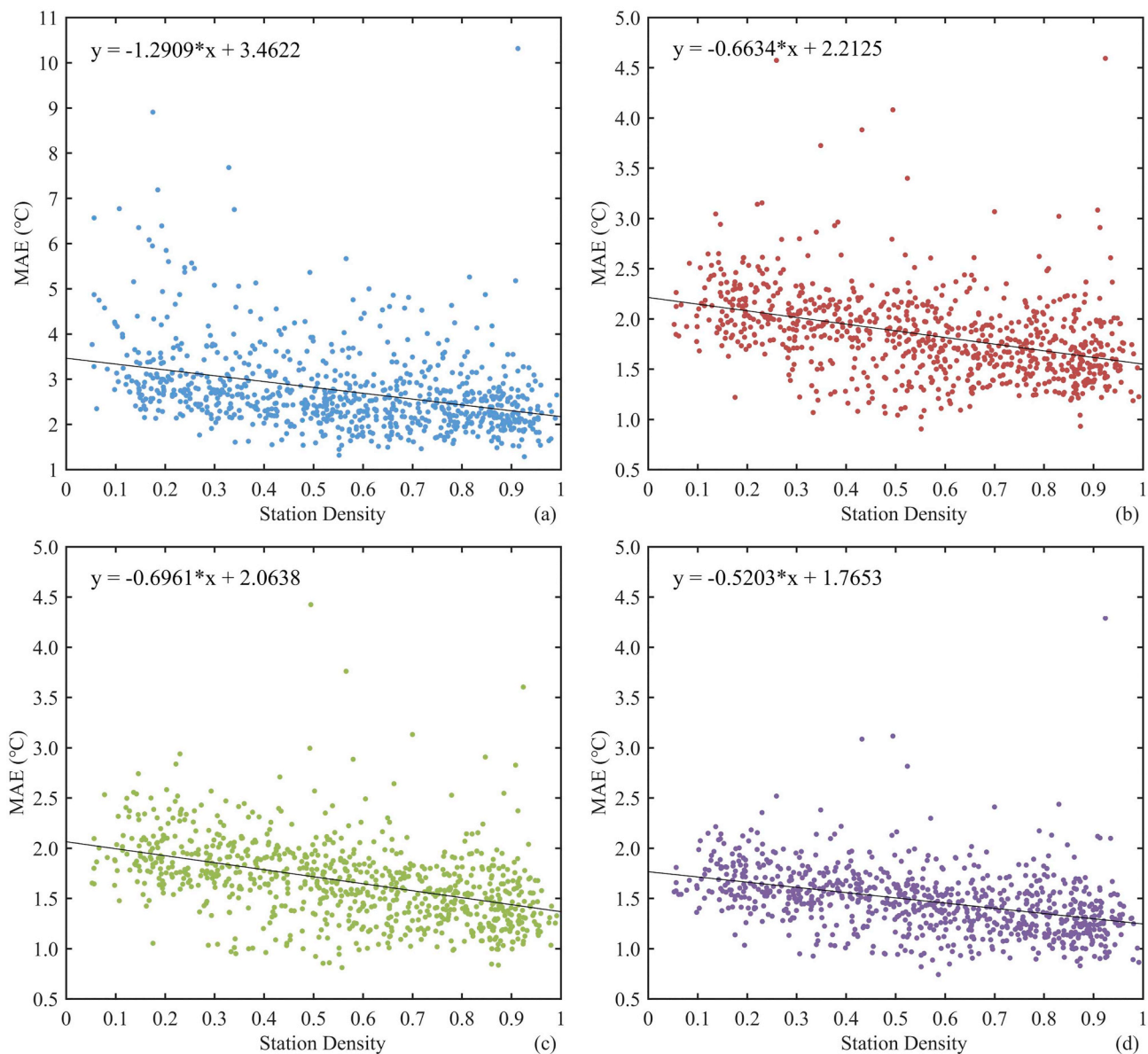


Fig. 7. The effect of station density on model performance. (a) MLR, (b) BPNN, (c) RF, (d) DBN.

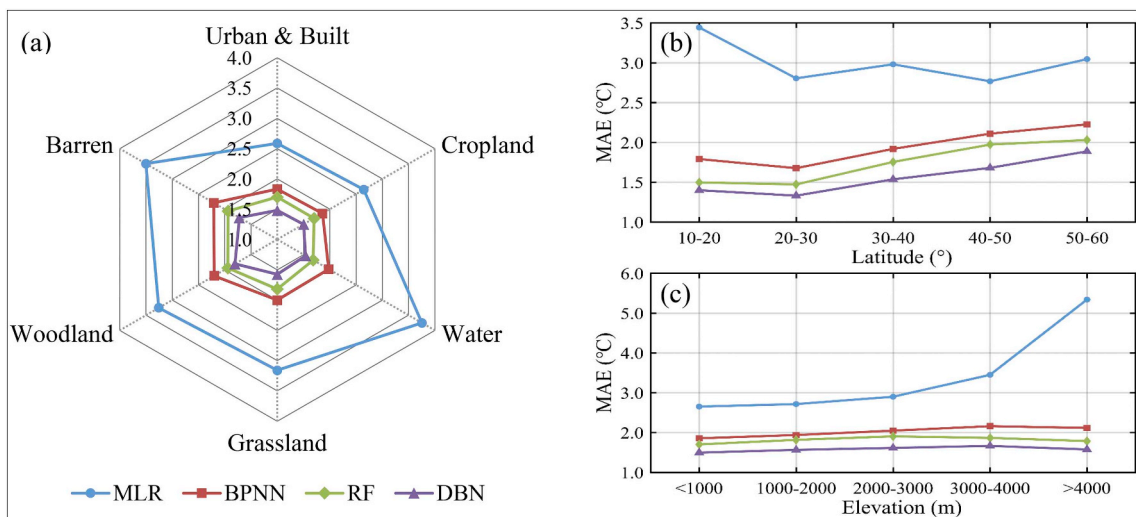


Fig. 8. Model performance for specific (a) land cover types, (b) latitude ranges and (c) elevation ranges.

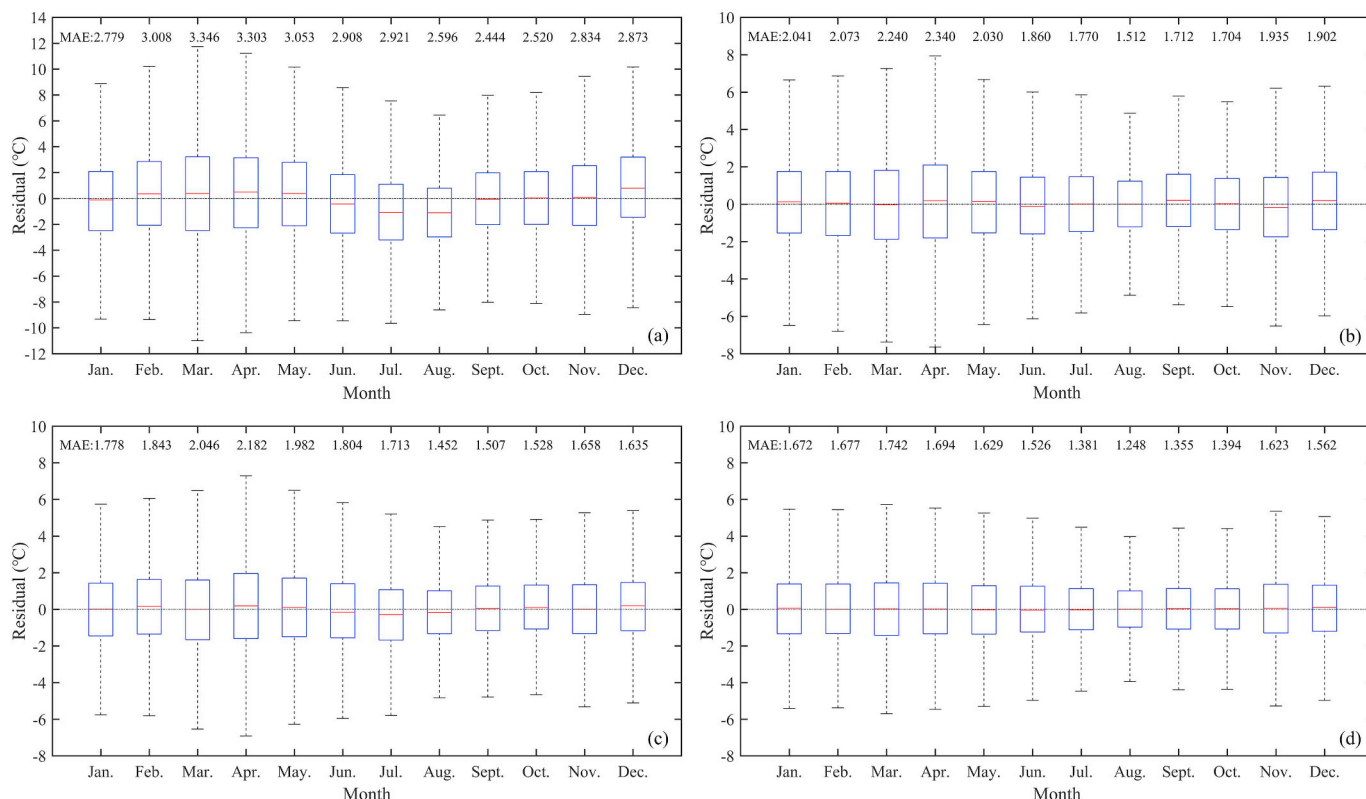


Fig. 9. Box plots of residuals for specific month. (a) MLR, (b) BPNN, (c) RF, (d) DBN.

Table 3

DBN model performance for different layers and neurons.

DBN hidden layer	Hidden layer neurons	RMSE (°C)	MAE (°C)	R
1	25	2.450	1.899	0.978
2	25 20	2.188	1.689	0.983
3	25 20 15	1.996	1.539	0.986
4	25 20 15 10	1.979	1.525	0.986

hidden layers, one input layer and one output layer is chosen in this study finally. The number of neurons in each hidden layer is designed as 25, 20 and 15, respectively.

### 5.2. DBN performance with different variables

As stated, the DBN model is more promising than the other three conventional methods in Ta estimation. In addition, several types of datasets were fused in this study and some of the variables were even not linearly related to Ta as described in Section 4.1. To better understand the actual contribution of each dataset made to the DBN model, the model accuracy was evaluated with different combinations of the datasets. The statistical indicators for each combination are provided in Table 4. When only remotely sensed data are included in the DBN model, the RMSE, MAE and R is 3.099 °C, 2.379 °C, and 0.965, respectively. Compared with this basic estimated result, model accuracy is obviously improved when more variables are introduced in the model. For socioeconomic data and assimilation data, the MAE is decreased from 2.379 °C to 2.118 °C and 2.145 °C, respectively. In addition, it should be noted that the geographical and temporal parameters were not strongly related to Ta but improved the model accuracy to a large extent. This phenomenon indicates that deep learning can effectively simulate the non-linear relationship between Ta and some predictor variables. Notably, the MAE of the combination R + S + A + P is decreased although it only changes a little compared with R + P,

Table 4

Model accuracy for different combinations of datasets.

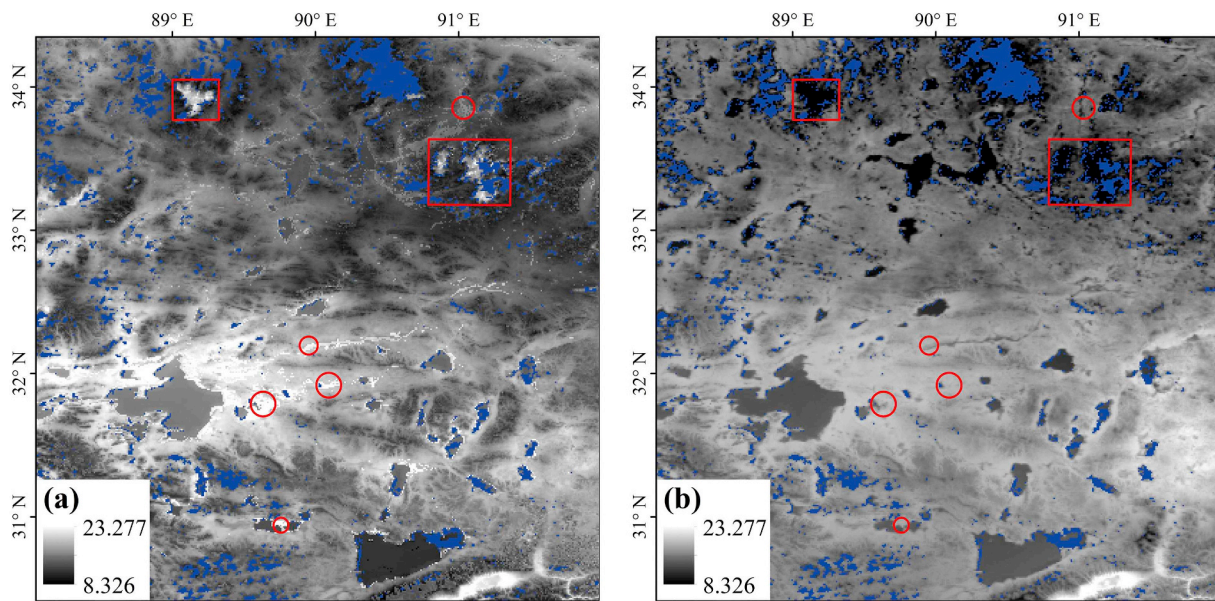
Datasets combinations	RMSE (°C)	MAE (°C)	R
R	3.099	2.379	0.965
R + S	2.763	2.118	0.972
R + A	2.790	2.145	0.972
R + P	2.145	1.655	0.983
R + S + A	2.041	2.653	0.974
R + S + P	2.049	1.579	0.985
R + A + P	2.066	1.595	0.985
R + S + A + P	1.995	1.539	0.986

R: remotely sensed data; P: geographical and temporal parameters; S: socioeconomic data; A: assimilation data.

R + S + P and R + A + P. More importantly, the model accuracy for these different dataset combinations confirms that fusing multi-source data in the model actually make sense in Ta estimation. On the other hand, the mapping results will be optimized with more detailed information in spatial when more datasets are utilized.

### 5.3. Analysis of uncertainties in mapping results

Although deep learning showed superior overall and spatio-temporal model performance, and the variables introduced in the model truly improved the estimation accuracy, there are still two issues should be considered. The first point is that spatial over-fitting is a common problem in estimation researches, which means the model can perform well for the time series of stations, but fail in the estimation for some unknown locations, especially in some complicated and untrained area (Meyer et al., 2018, 2016). After many experiments, we found that the 16-days resolution NDVI data used in the model would lead to mapping outliers. The possible reason for this phenomenon may be that the model is unable to well fit the variable values with a regular temporal resolution of 16-days to the daily scale. The other point is that “nugget



**Fig. 10.** Spatial distribution of (a)  $T_a$  estimated by using all variables and (b)  $T_a$  estimated after removing the NDVI and Lc over the local area for the 210th day (unit:  $^{\circ}\text{C}$ ). The blue pixels represent no data value. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

effects” phenomenon may be easily encountered when the variable value has a large variation in space or with regular spatial patterns (Molotch et al., 2005). To solve this problem, elevation and the population density data were processed by an exponential function as mentioned in Section 2.2.5. However, Lc data used in this study shows a regular distribution in space, which makes the results easily lead to “nugget effects” phenomenon. Considering that Lc does not represent a specific value, pre-processing the values seems to make no sense. Taking a local area for the 210th day as an example, the spatial distribution of the  $T_a$  estimated by using all variables and the  $T_a$  estimated after removing the NDVI and Lc are presented in Fig. 10. As shown in Fig. 10a, “nugget effects” phenomenon can be obviously observed in the areas marked in the red circle. Additionally, some snow or ice-covered areas inside the red box shown in Fig. 10a present obvious higher estimations than surrounding areas, which is not consistent with the facts. Fortunately, after removing the NDVI and Lc, it can be seen clearly in Fig. 10b that these uncertainties in mapping results have been well addressed. More importantly, there was only a slight reduction in the model accuracy after removing these two variables, and the RMSE, MAE and R are 2.079  $^{\circ}\text{C}$ , 1.606  $^{\circ}\text{C}$ , 0.984, respectively. As a consequence, NDVI and Lc were removed as misleading variables for the DBN-based mapping of  $T_a$  across China.

#### 5.4. Spatio-temporal distributions of $T_a$

After solving the over-fitting and “nugget effects” phenomenon in the mapping results, the  $0.01^{\circ}$  spatial resolution daily maximum  $T_a$  can be generated by the DBN model with accurate estimations. Taking the annual estimated  $T_a$  map as an example, we compared it with the corresponding assimilated  $T_a$  map provided by the GLDAS (Fig. 11). It should be noted that assimilated  $T_a$  were provided by the GLDAS as instantaneous variables with a 3-hourly resolution. Here, we calculated the maximum of eight  $T_a$  values per day as the daily maximum  $T_a$  value for each pixel. Additionally, assimilated  $T_a$  over water areas are not simulated by the GLDAS. In Fig. 11, the annual  $T_a$  for the DBN model shows a similar spatial distribution with the assimilated  $T_a$ , which suggests that DBN can well fit the general trend of  $T_a$  in space. Moreover, the DBN model exhibits more detailed spatial variations than the assimilated results, especially for some complex areas. For instance, the assimilated  $T_a$  in northwestern and southwestern China appears

obvious pixel effect due to the low spatial resolution. These comparisons confirm the superiority of the DBN model and lend our confidence to advocate the DBN model in  $T_a$  estimation research in the future.

In addition,  $T_a$  mapping results for the four seasons are also presented in this study (Fig. 12). Seasonally, the continuous estimated  $T_a$  value ranges from  $-15$  to  $45^{\circ}\text{C}$  in 2015.  $T_a$  values are obviously higher in summer (June to August) and lower in winter (December to February), while spring (March to May) and autumn (September to November) show the similar estimated mapping results. Spatially, it's clear that seasonal  $T_a$  generally decreases from the eastern and southern areas to the northeastern and southwestern areas, which is consistent with the physical situation.  $T_a$  values in summer are generally high, except for the high-elevation areas like the Tibetan plateau. In addition, water areas show lower  $T_a$  values than the surrounding land areas while the urban zones show relatively higher  $T_a$  than surrounding rural zones. These different trends may be caused by several factors, like topography condition, climate difference and social activity effects.

## 6. Conclusions

In this study, the 5-layers DBN model, as a typical deep learning method, was employed to estimate  $T_a$  for the first attempt. Specific, we estimated the spatially continuous  $0.01^{\circ}$  daily maximum  $T_a$  across China by fusing remote sensing, station, simulation and socioeconomic data. Compared with conventional methods, the validation results showed that deep learning method could better take the non-linear relationship into consideration and achieved the best overall model performance with the RMSE of 1.996  $^{\circ}\text{C}$ , MAE of 1.539  $^{\circ}\text{C}$ , and R of 0.986. In addition, comprehensive analyses of the model performance for specific space and time were discussed, more accurate estimations could be obtained by using the DBN model. The performance of the DBN model with different combinations of datasets indicated that introduce effective variables in the model could improve the model performance to a great extent. Spatio-temporal  $T_a$  estimated by the DBN model showed more detailed spatial variations than assimilated  $T_a$ . Moreover, relevant researches can also be extended to the estimation of daily minimum and mean  $T_a$  in the future.

It must be emphasized that there are still several limitations in our study. On the one hand, although effective multi-source datasets can obviously improve the accuracy of the models, how to scientifically

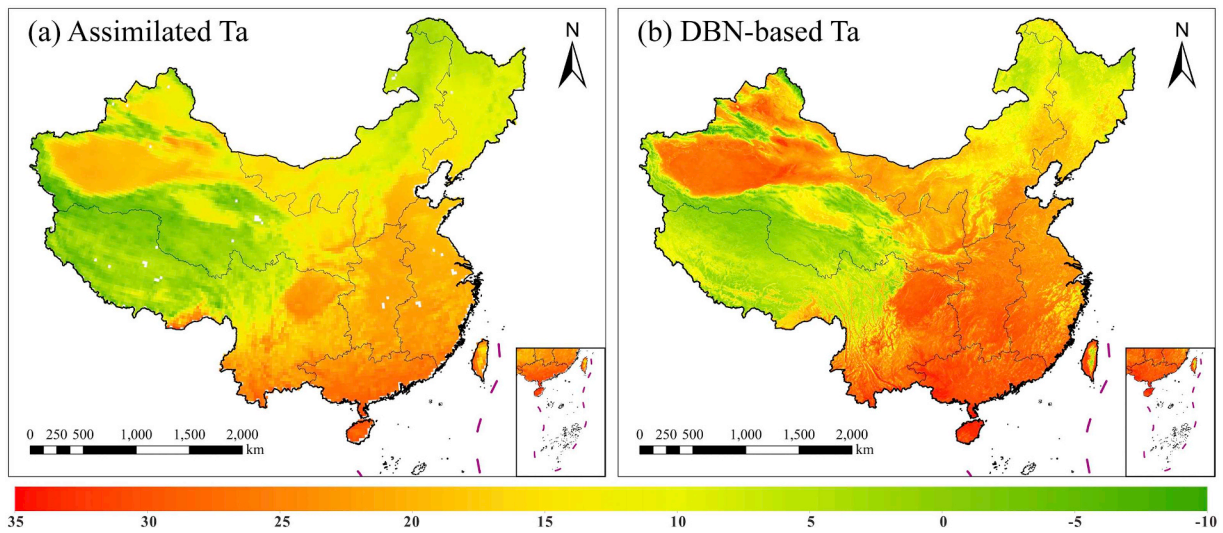


Fig. 11. Comparison of the annual daily maximum Ta map (unit: °C). (a) Assimilated Ta and (b) DBN-based Ta. The pixels in white represent no data values.

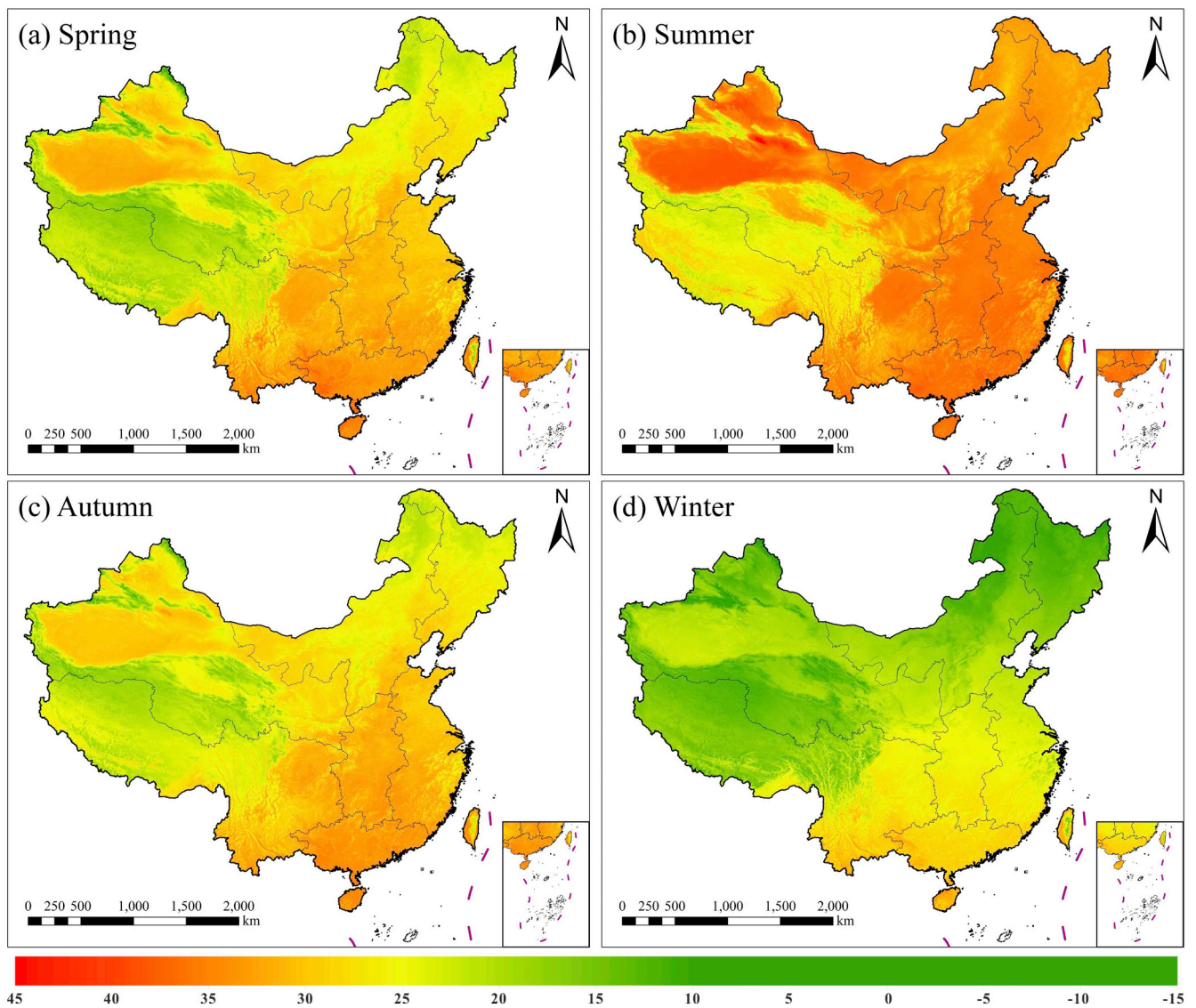


Fig. 12. The spatial patterns of seasonal Ta across China in 2015 estimated by the DBN model (unit: °C). (a) Spring, (b) summer, (c) autumn, (d) winter. The pixels in white represent no data values.

eliminate variables which are prone to lead uncertainties in mapping results is still a challenge. On the other hand, vacancy values reconstruction to improve the spatial coverage of LSTD data and quality assurance to ensure data availability need further exploration. Thus, future work should focus more attention on the missing information reconstruction of the estimated  $T_a$  caused by the incomplete LSTD. Finally, different models for specific regions and seasons at the national scale may worth further examination to improve the model performance.

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